

**Technical University of Košice**  
**Faculty of Electrical Engineering and Informatics**

**Modification of gl.inet board for  
communication with peripheral devices**

**Master's Thesis**

**2013**

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**Technical University of Košice**  
**Faculty of Electrical Engineering and Informatics**

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communication with peripheral devices**

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**Košice 2013**

**Peter Babič**

# Errata

## Modification of gl.inet board for communication with peripheral devices

Peter Babič

Košice 2013

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12	6	publikácia	prezentácia
22	23	internet	intranet

## **Abstract**

Text abstraktu v svetovom jazyku je potrebný pre integráciu do medzinárodných informačných systémov. Ak nie je možné cudzojazyčnú verziu abstraktu umiestniť na jednej strane so slovenským abstraktom, je potrebné umiestniť ju na samostatnú stranu (cudzojazyčný abstrakt nemožno deliť a uvádzať na dvoch stranách).

## **Keywords**

Optimization, thesis, writing

## **Abstrakt**

Abstrakt je povinnou súčasťou každej práce. Je výstižnou charakteristikou obsahu dokumentu. Nevyjadruje hodnotiace stanovisko autora. Má byť taký informatívny, ako to povoľuje podstata práce. Text abstraktu sa píše ako jeden odstavec. Abstrakt neobsahuje odkazy na samotný text práce. Mal by mať rozsah 250 až 500 slov. Pri štylizácii sa používajú celé vety, slovesá v činnom rode a tretej osobe. Používa sa odborná terminológia, menej zvyčajné termíny, skratky a symboly sa pri prvom výskyte v texte definujú.

## **Klíčové slová**

Optimalizácia, záverečná práca, písanie

## **Assign Thesis**

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## **Declaration**

I hereby declare that this thesis is my own work and effort. Where other sources of information have been used, they have been acknowledged.

Košice, April 24, 2013

.....

*Signature*

## **Acknowledgement**

I would like to express my sincere thanks to my supervisor Dr Vojtech Čierny, PhD, the main Supervisor. Special mention should go to Dr Matej Biely, CSc. for his constant, and constructive guidance throughout the study. To all other who gave a hand, I say thank you very much.

## Preface

Predhovor (*Preface*) je povinnou náležitostí záverečnej práce, pozri V predhovore autor uvedie základné charakteristiky svojej záverečnej práce a okolnosti jej vzniku. Vysvetlí dôvody, ktoré ho viedli k voľbe témy, cieľ a účel práce a stručne informuje o hlavných metódach, ktoré pri spracovaní záverečnej práce použil.



# Contents

<b>Introduction</b>	<b>1</b>
<b>1 Electric power fundamentals</b>	<b>2</b>
1.1 Ohm's law . . . . .	2
1.2 Direct current (DC) circuits . . . . .	3
1.3 Waveforms and alternating current (AC) circuits . . . . .	3
1.4 Power in AC circuits . . . . .	4
1.5 Phasor and phase difference . . . . .	5
1.6 Power factor . . . . .	6
1.7 Electric power measurement . . . . .	6
1.8 Power measuring Integrated Circuits . . . . .	7
<b>2 Embedded system</b>	<b>9</b>
2.1 Processing units . . . . .	9
2.2 System-on-chip . . . . .	9
2.3 Operating system . . . . .	10
2.4 Real-time operating system . . . . .	10
2.5 Embedded Linux . . . . .	11
2.6 Kernel . . . . .	11
2.7 OpenWRT . . . . .	12
2.8 Components of the OpenWRT . . . . .	12
<b>3 GL.inet board</b>	<b>13</b>
3.1 Atheros AR9331 wi-fi System-on-Chip . . . . .	13
3.2 From TL-WR703N to GL.inet . . . . .	14
<b>4 ESP8266 wi-fi node</b>	<b>16</b>
<b>5 Requirements</b>	<b>17</b>
5.1 Hardware requirements . . . . .	17
5.2 Software requirements . . . . .	18
5.3 System description . . . . .	18
5.4 The TCP/IP networking protocol . . . . .	20
<b>6 Main part of Thesis</b>	<b>21</b>
<b>7 Conclusion</b>	<b>22</b>

References	23
Appendices	24
Appendix A	25
Appendix B	26
Appendix C	28

## List of Figures

1–1	The common types of waveforms visualised as a function of amplitude	3
1–2	The phase difference between voltage (blue) and current (red), the origin of phase difference of angle $\varphi$	6
1–3	The simplified block diagram for a power measurement integrated circuit (IC)	7
2–1	The simplified view on the Linux system structure	12
3–1	The block diagram of the Atheros AR9331 System-on-Chip (SoC) used as a main processing unit on GL.inet board	14
3–2	The front side of the GL.inet board exposing the main Atheros SoC, Random-access memory (RAM) and interfaces	15
3–3	The back side of the GL.inet board exposing the Flash memory and a main voltage regulator	15
5–1	The block diagram of a <i>server</i> node of a proposed system, including hardware requirements	18
5–2	The block diagram of a <i>client</i> node of a proposed system, including hardware requirements	19

**List of Tables**

3-1 The basic characteristics of the GL.inet board . . . . . 13

## Acronyms

<b>AC</b>	Alternating Current
<b>ADC</b>	Analog-to-digital converter
<b>AP</b>	Access Point
<b>ASIC</b>	Application-specific integrated circuit
<b>BSD</b>	Berkeley Software Distribution
<b>CLI</b>	Command-line interface
<b>CPU</b>	Central processing unit
<b>DAC</b>	Digital-to-analog converter
<b>DC</b>	Direct Current
<b>DDR</b>	Double data rate synchronous DRAM
<b>DRAM</b>	Dynamic random-access memory
<b>DSP</b>	Digital signal processor
<b>EEPROM</b>	Electrically erasable programmable ROM
<b>FPGA</b>	Field-programmable gate array
<b>GPIO</b>	General-purpose I/O
<b>GUI</b>	Graphical user interface
<b>HW</b>	hardware
<b>Hz</b>	Hertz, the SI unit of frequency
<b>I/O</b>	Input/Output
<b>I<sup>2</sup>S</b>	Integrated Interchip Sound
<b>IC</b>	integrated circuit
<b>IEEE</b>	Institute of Electrical and Electronics Engineers
<b>IP</b>	Internet Protocol
<b>JTAG</b>	Joint test action group
<b>LAN</b>	Local area network
<b>LED</b>	Light emitting diode
<b>LNA</b>	Low-noise amplifier
<b>LPCC</b>	Quad Flat No-leads
<b>MAN</b>	Metropolitan are network
<b>MB</b>	Mega-Byte, unit of digital information
<b>MHz</b>	Mega-Hertz
<b>MIPS</b>	Microprocessor without Interlocked Pipeline Stages
<b>OS</b>	Operating system

**PA** Power amplifier  
**PCM** Pulse code modulation  
**PDA** Personal digital assistant  
**POSIX** Portable operating system interface  
**RAM** Random-access memory  
**RF** Radio frequency  
**RMS** Root-mean square  
**ROM** Read-Only memory  
**RTOS** Real-time operating system  
**S/PDIF** Sony-Philips Digital Interface Format  
**SDR** Synchronous dynamic random access memory  
**SLIC** Subscriber line interface circuit  
**SoC** System-on-Chip  
**SPI** Serial peripheral interface  
**SW** software  
**TCP** Transmission Control Protocol  
**TCP/IP** Transmission Control Protocol/Internet Protocol  
**UART** Universal asynchronous receiver/transmitter  
**USB** Universal serial bus  
**VOIP** Voice over IP  
**WAN** Wide area network  
**WLAN** Wireless local area network

## List of Terms

- android** a mobile Operating system (OS) based on the Linux kernel and currently developed by Google, designed primarily for touchscreen mobile devices such as smartphones and tablet computers, and for specialized user interfaces like televisions (Android TV), cars (Android Auto), and wrist watches (Android Wear).
- application** a program, or group of programs, that is designed for the end user
- cloud** (computing) is a model for enabling ubiquitous, convenient, on-demand access to a shared pool of configurable computing resources
- command** a directive to a computer program acting as an interpreter of some kind, in order to perform a specific task, commonly a directive to some kind of Command-line interface (CLI), such as a shell
- compiler** a computer program (or set of programs) that transforms source code written in a programming language (the source language) into another computer language (the target language, often having a binary form known as object code)
- computer** a programmable machine, that responds to a specific set of instructions in a well-defined manner and can execute a prerecorded list of instructions (a program).
- daemon** a computer program running on the multi-tasking OSes in a background, rather than being under the direct control of an interactive user
- datasheet** a document that summarizes the performance and other technical characteristics of a product, machine, component (e.g., an electronic component)
- driver** a computer program that operates or controls a particular type of device that is attached to a computer
- ethernet** family of computer networking technologies for Local area networks (LANs) and Metropolitan area networks (MANs), conforming to standard Institute of Electrical and Electronics Engineers (IEEE) 802.3
- firmware** the combination of a hardware (HW) device, e.g. an IC, and computer instructions and data that reside as read only software (SW) on that device, it usually cannot be modified during normal operation of the device

<b>flash</b>	an electronic non-volatile computer storage medium (memory) that can be electrically erased and reprogrammed, next evolution of Electrically erasable programmable ROM (EEPROM)
<b>interface</b>	a shared boundary across which two separate components of a computer system exchange information that can occur between SW, computer HW, peripheral devices, humans and combinations of these
<b>kernel</b>	a computer program that manages Input/Output (I/O) requests from software, and translates them into data processing instructions for the central processing unit and other electronic components of a computer, being a fundamental part of a modern computer's OS
<b>library</b>	a collection of programs and SW packages made generally available, often loaded and stored on disk for immediate use
<b>linux</b>	an Unix-like and mostly POSIX-compliant computer OS assembled under the model of free and open-source SW development and distribution, from the beginning maintained by Linus Torvalds
<b>network</b>	a medium that allows computing devices pass data to each other along links (data connections)
<b>peripheral</b>	a device that is connected to and works with a computer in a some way, but is not essential to a computer's function
<b>program</b>	a specific set of ordered operations for a computer to perform
<b>router</b>	a networking device that forwards data packets between computer networks, connected to two or more data lines from different networks
<b>shell</b>	a user interface for access to an OS's services, using either CLI or Graphical user interface (GUI), depending on a computer's role and particular operation
<b>stack</b>	(protocol) is an implementation of a computer networking protocol suite, used interchangeably
<b>system</b>	a set of interacting or interdependent components forming an integrated whole, observing properties not obtainable with individual components
<b>unix</b>	a family of multi-taskings, multi-user computer OS that derive from the original AT&T Unix, developed in the 1970s at the Bell Labs research center by Ken Thompson, Dennis Ritchie, and others



**utility** is system SW designed to help analyze, configure, optimize or maintain a computer

## Introduction

V úvode autor podrobnejšie ako v predhovore, pritom výstižne a krátko charakterizuje stav poznania alebo praxe v špecifickej oblasti, ktorá je predmetom záverečnej práce. Autor presnejšie ako v predhovore vysvetlí ciele práce, jej zameranie, použité metódy a stručne objasní vzťah práce k iným prácam podobného zamerania. V úvode netreba zachádzať hlbšie do teórie. Nie je potrebné podrobne popisovať metódy, experimentálne výsledky, ani opakovať závery prípadne odporúčania, pozri.

# 1 Electric power fundamentals

In general physics terms, power is defined as the rate at which energy is transferred (or transformed). Electric energy in particular, begins as electric potential energy – what we commonly refer to as voltage. When electrons flow through that potential energy, it turns into electric energy. In most useful circuits, that electric energy transforms into some other form of energy. Electric power is measured by combining both how much electric energy is transferred, and how fast that transfer happens.

The electric power  $P$  is equal to the energy consumption  $E$  divided by the consumption time  $t$

$$P = \frac{E}{t}$$

where  $P$  is the electric power in watt [W],  $E$  is the energy consumption in joule [J] and  $t$  is the time in seconds [s].

Electrical Power, in a circuit is the amount of energy that is absorbed or produced within the circuit. A source of energy such as a voltage will produce or deliver power while the connected load absorbs it. Light bulbs and heaters for example, absorb electrical power and convert it into heat or light. The higher their value or rating in watts the more power they will consume.

## 1.1 Ohm's law

Ohm's Law deals with the relationship between voltage and current in an ideal conductor. This relationship states that: The potential difference (voltage) across an ideal conductor is proportional to the current through it [5]. The constant of proportionality is called the *resistance*.

$$I = \frac{U}{R}$$

where  $I$  is the current expressed in Amperes [A],  $V$  is the voltage, bearing the Volt units [V] and  $R$  is the electrical resistance in ohms [ $\Omega$ ].

The Ohm's law can be further expanded, to get these three quantities in relationship with **power**, such as

$$P = I \cdot V = I^2 \cdot R = \frac{U^2}{R}$$

## 1.2 Direct current (DC) circuits

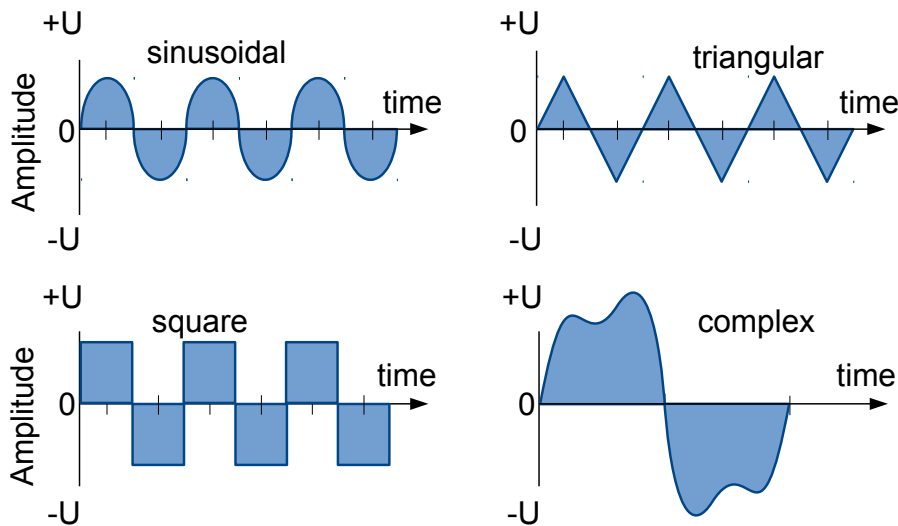
Generally, Ohm's law is used on Direct Current (DC) circuits. A DC voltage or current has a fixed magnitude (amplitude) and a definite direction associated with it. Both DC currents and voltages are produced by power supplies, batteries, dynamos and solar cells to name a few.

We also know that DC power supplies do not change their value with regards to time, they are a constant value flowing in a continuous steady state direction. In other words, DC maintains the same value for all times and a constant uni-directional DC supply never changes or becomes negative unless its connections are physically reversed.

## 1.3 Waveforms and alternating current (AC) circuits

An alternating function or Alternating Current (AC) waveform on the other hand is defined as one that varies in both magnitude and direction in more or less an even manner with respect to time making it a "bi-directional" waveform [9]. An AC function can represent either a power source or a signal source with the shape of an AC waveform generally following that of a mathematical sinusoid as defined by

$$A(t) = A_{max} \cdot \sin(2\pi ft)$$



**Figure 1 – 1** The common types of waveforms visualised as a function of amplitude

The term AC or to give it its full description of Alternating Current, generally refers to a time-varying waveform with the most common of all being called a **Sinusoid** better known as a **Sinusoidal Waveform**. Sinusoidal waveforms are

more generally called by their short description as **Sine Waves**. Sine waves are by far one of the most important types of AC waveform used in electrical engineering.

This means then that the AC waveform is a “time-dependent signal” with the most common type of time-dependant signal being that of the Periodic Waveform. The periodic or AC waveform is the resulting product of a rotating electrical generator. Generally, the shape of any periodic waveform can be generated using a fundamental frequency and superimposing it with harmonic signals of varying frequencies and amplitudes but that is out of the waveform fundamentals theory

Alternating voltages and currents can not be stored in batteries or cells like direct current (DC) can, it is much easier and cheaper to generate these quantities using alternators or waveform generators when they are needed. The type and shape of an AC waveform depends upon the generator or device producing them, but all AC waveforms consist of a zero voltage line that divides the waveform into two symmetrical halves. The main characteristics of an AC waveform are defined as:

- the **period (T)** is the length of time in seconds that the waveform takes to repeat itself from start to finish. This can also be called the Periodic Time of the waveform for sine waves, or the Pulse Width for square waves
- the **frequency** is the number of times the waveform repeats itself within a one second time period. Frequency is the reciprocal of the time period, defined as  $f = \frac{1}{T}$ , with the unit of frequency being the Hertz [Hz]
- the **amplitude** is the magnitude or intensity of the signal waveform

## 1.4 Power in AC circuits

When a reactance (either inductive or capacitive) is present in an AC circuit, the Ohm’s law formula does not apply and different approach must be taken to express and calculate power.

**Real power** (or true power) is the power that is used to do the work on the load:

$$P = U_{RMS} \cdot I_{RMS} \cdot \cos \varphi$$

where P is the real power in watts,  $U_{RMS}$  is the Root-mean square (RMS) voltage, defined as  $U_{peak}/\sqrt{2}$  in volts,  $I_{RMS}$  is the RMS current, defined as  $I_{peak}/\sqrt{2}$  in amperes and  $\varphi$  is the impedance phase angle - phase difference between voltage and current.

**Reactive power** on the other hand, is the power that is wasted and not used to do work on the load. Curiously, it is defined as

$$Q = U_{RMS} \cdot I_{RMS} \cdot \sin \varphi$$

with  $Q$  being the reactive power in volt-ampere-reactive [var].

**Apparent power** is the power that is supplied to the circuit. Definition:

$$S = U_{RMS} \cdot I_{RMS}$$

where the unit of apparent power  $S$  is volt-ampere [VA]. It can be seen that it is not phase-angle dependent.

The relation all these three quantities are in is defined as

$$P^2 + Q^2 = S^2$$

however, again, nothing in the real world is perfect, and this relation only applies for a perfectly **sinusoidal waveforms!**

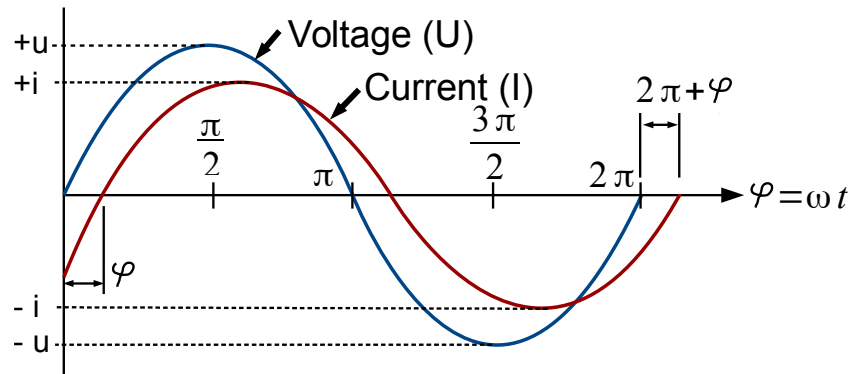
## 1.5 Phasor and phase difference

A phasor is a constant complex number representing the complex amplitude (magnitude and phase) of a sinusoidal function of time. It is usually expressed in exponential form. Phasors are used in engineering to simplify computations involving sinusoids, where they can often reduce a differential equation problem to an algebraic one. The origin of the word phasor comes from phase + vector.

Phasor is a vector that represents a sinusoidally varying quantity, as a current or voltage, by means of a line rotating about a point in a plane, the magnitude of the quantity being proportional to the length of the line and the phase of the quantity being equal to the angle between the line and a reference line.

Considering the figure 1–2, the voltage waveform above starts at zero along the horizontal reference axis, but at that same instant of time the current waveform is still negative in value and does not cross this reference axis until 30° later. Then there exists a Phase difference between the two waveforms as the current cross the horizontal reference axis reaching its maximum peak and zero values after the voltage waveform.

As the two waveforms are no longer “in-phase”, they must therefore be “out-of-phase” by an amount determined by phi,  $\varphi$  and in our example this is 30°. It



**Figure 1 – 2** The phase difference between voltage (blue) and current (red), the origin of phase difference of angle  $\varphi$

can now be said, that the two waveforms are now  $30^\circ$  out-of phase. The current waveform can also be said to be “lagging” behind the voltage waveform by the phase angle  $\varphi$  [8].

## 1.6 Power factor

also power factor correction

## 1.7 Electric power measurement

Measuring the electric power makes most sense on the customer appliances. The first reason is, that they generally consume power that is purchased on contract. The energetic company measures all the power used up by the end customer, but customer has no easy way to see how much and how *effectively* is power used by the appliances. The second important reason is that the appliances has a standardised connector (plug) that is guaranteed to fit in all the area using it, which is not a case for example on battery powered devices (batteries has different sizes, connectors and general properties).

When it comes to measuring the electrical power, the first and the most important thing to discuss is safety. Only after all the safety precautions had been made clear, the theory can be clarified and subsequently, the practice can be applied.

If not handled with care, operating or manipulating with voltage can cause permanent damage to appliance or health, or can cause fire or even death. Thus, respect, increased care and knowledge is necessary in all further practical steps involved.

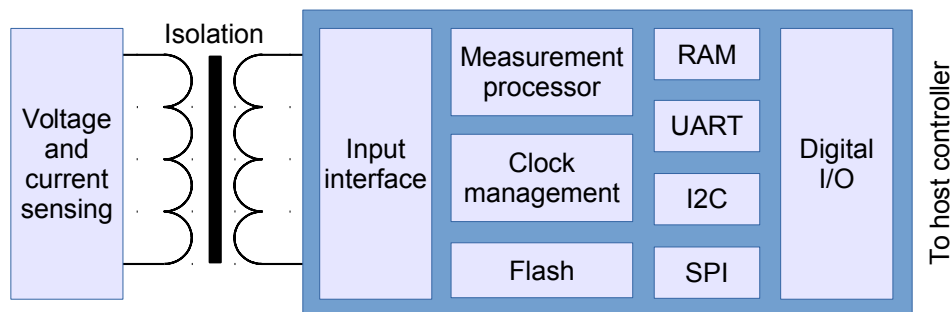
## 1.8 Power measuring Integrated Circuits

Although it is possible to construct a circuit out of discrete components that would measure the mentioned quantities, and such a solution would probably be the cheapest solution out there, it would be highly impractical due to multiple reasons.

The most importantly, the obtained accuracy of the measurements would be dependent on the implementation and used components. It is safe to assume, that without multiple design iterations, the accuracy may be too low to be used in practice.

Another point is that, there is no definitive guide, ready to follow, about how to design such circuit. The reason of this is the vast amount of components available on the market and a lot of design considerations to take into account, depending on the requirements.

A special purpose integrated circuits (ICs) are being developed for the exact purpose of measuring the real, apparent and reactive power, the power factor, and in most cases, gathering some other relevant information.



**Figure 1–3** The simplified block diagram for a power measurement IC

From the block diagram 1–3, it can be seen that the power measuring IC is just a specialised microcontroller. It takes the data from the sensing circuitry, which in case of voltage can be measured *directly*, provided that the galvanic isolation is included, for the sake safety. The current however, must be measured *indirectly*. There are three common ways of doing so:

1. **shunt resistor** - a resistor with a very small but precise value, that causes a voltage drop with a current passing through it due to the Ohm's law, regardless of frequency. The actual voltage drop is so small, that it can be assumed insignificant. However, the voltage drop is still present and may



cause some issues, if not taken into account. The advantage is really low price. External galvanic isolation must be provided.

2. **current transformer** - a current passing wire inside a current sensing coil. Since it is a magnetic induction based transformer, the galvanic isolation is naturally present. The disadvantage is, that the transformer has a cut-off after which it's effect diminishes rapidly. External magnetic fields can cause problems too. Suitable for measuring current of a fixed (or non-decreasing) frequency.
3. **Hall-effect sensor** - a sensor measuring absolute electromagnetic field in a conductor. In contrast to the current transformer, this sensor is able to measure low frequency currents, down to DC, which is a feat that the shunt resistor possesses too. Can be placed anywhere near the current path and doesn't require physical connection, thus providing galvanic isolation too. The price increases with operating currents range and precision. Prone to external magnetic fields too.

Using dedicated power measuring IC has another advantage apart from being more accurate. In fact, the part datasheet can be consulted and if all application notes and advices are abided, the specified accuracy can be guaranteed.

## 2 Embedded system

An embedded system is some combination of computer hardware (HW) and software (SW), either fixed in capability or programmable, that is specifically designed for a particular function [3]. Industrial machines, automobiles, medical equipment, cameras, household appliances, airplanes, vending machines and toys (as well as the more obvious cellular phone and Personal digital assistant (PDA)) are among the myriad possible hosts of an embedded system. Embedded systems that are programmable are provided with programming interfaces, and embedded systems programming is a specialized occupation.

### 2.1 Processing units

The term embedded system is quite broad, so there is no surprise that the spectrum of used processing units is also wide. Since the general purpose microprocessors require external components, namely memories and peripherals, they tend to consume extra power and a board space. Since the design limitations of an embedded systems are most of the time low physical size, low power consumption and/or long uptime and ruggedness (more components mean more parts could fail), microprocessors are seldom used. However, most of the commonly used architectures and word lengths are covered. Due to aforementioned reasons, microcontrollers are favored over microprocessors.

### 2.2 System-on-chip

Today's state of chip integration allows production costs of a complex system on chip devices to be relatively low, thus making System-on-Chip (SoC) attractive choice for embedded systems. SoCs could be described as an IC that integrates all components of a computer or other electronic system into a single chip. It may contain digital, analog, mixed-signal, and often Radio frequency (RF) functions - all on a single chip substrate [2]. SoCs are very common in the mobile electronics market because of their low power consumption. A typical SoC consists of (specific block diagram can be seen on 3-1):

- a microcontroller, microprocessor or Digital signal processor (DSP) core(s)
- memory blocks including a selection of Read-Only memory (ROM), Random-access memory (RAM), Electrically erasable programmable ROM (EEPROM) and Flash
- timing sources including oscillators and phase-locked loops

- peripherals including counter-timers, real-time timers and power-on reset generators
- external interfaces, including industry standards such as Universal serial bus (USB), FireWire, Ethernet, Universal asynchronous receiver/transmitter (UART), Serial peripheral interface (SPI)
- analog interfaces including Analog-to-digital converters (ADCs) and Digital-to-analog converters (DACs)
- voltage regulators and power management circuits
- a bus connecting these blocks

SoCs can be implemented as an Application-specific integrated circuit (ASIC) or using a Field-programmable gate array (FPGA).

## 2.3 Operating system

An Operating system (OS) is a computer program that supports a computer's basic functions, and provides services to other programs (or applications) that run on the computer. The applications provide the functionality that the user of the computer wants or needs. The services provided by the operating system make writing the applications faster, simpler, and more maintainable.

Over time, a lot of embedded OSes suited for embedded systems were developed. An embedded OS is a type of OS that is embedded and specifically configured for a certain HW configuration. HW that uses embedded OS is designed to be lightweight and compact, forsaking many other functions found in non-embedded (i.e. desktop) computer systems in exchange for efficiency at resource usage [6]. This means that they are made to do specific tasks and do them efficiently. Notable embedded OSes currently in use by consumers include:

- **Embedded Linux** - used in many other devices like printers, routers or smart TVs; Android is a derivative of embedded Linux
- **iOS** - subset of Mac OS X, used in Apple's mobile devices Palm OS
- **Windows Mobile** - Microsoft's OS for mobile devices

## 2.4 Real-time operating system

A Real-time operating system (RTOS) is just a special purpose OS. The real time part of the name does not mean that the system responds quickly, it just means that there are rigid time requirements that must be met. If these

time requirements are not met, the results can become inaccurate or unreliable[7]. Embedded systems frequently possess the real time requirement. There are two kinds of RTOSes:

**Hard Real Time** - system delays are known or at least bounded. Said to be operating correctly if the system can return results within any time constraints.

**Soft Real Time** - critical tasks get priority over other tasks and will retain priority until the task is completed. This is another way of saying that real time tasks cannot be kept waiting indefinitely. Soft real time makes it easier to mix the system with other systems.

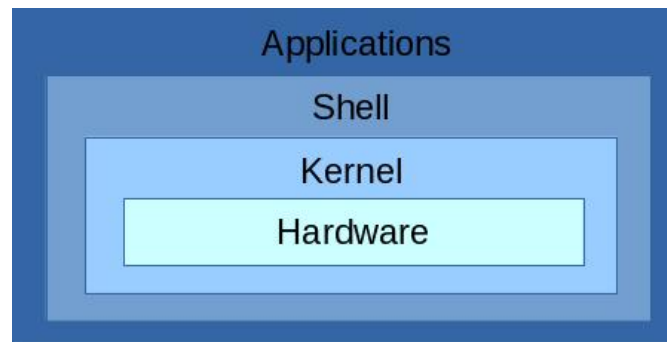
## 2.5 Embedded Linux

Linux itself is a kernel, but Linux in day to day terms rarely means so. Embedded Linux generally refers to a complete Linux distribution targeted at embedded devices. There is no Linux kernel specifically targeted at embedded devices, the same Linux kernel source code can be built for a wide range of devices, workstations, embedded systems, and desktops though it allows the configuration of a variety of optional features in the kernel itself. In the embedded development context, there can be an embedded Linux system which uses the Linux kernel and other software or an embedded Linux distribution which is a prepackaged set of applications meant for embedded systems and is accompanied by development tools to build the system[4].

With the availability of consumer embedded devices, communities of users and developers were formed around these devices: Replacement or enhancements of the Linux distribution shipped on the device has often been made possible thanks to availability of the source code and to the communities surrounding the devices. Due to the high number of devices, standardized build systems have appeared, namely OpenWRT.

## 2.6 Kernel

The kernel is the essential center of a computer OS, the core that provides basic services for all other parts of the OS [1]. It has complete control over what happens in the system. A kernel can be contrasted with a shell, the outermost part of an OS that interacts with user commands. Kernel and shell are terms used more frequently in Unix or Unix-like OSes than in IBM mainframe or Microsoft Windows systems.



**Figure 2–1** The simplified view on the Linux system structure

The simplified view on the Linux system structure can be seen on 2–1. It does not include device driver, compilers, daemons, utilities, commands, library files and such, but should be enough for a demonstration.

## 2.7 OpenWRT

OpenWrt is an OS (in particular, an embedded OS) based on the Linux kernel, primarily used on embedded devices to route network traffic. It has been optimized for size, to be small enough for fitting into the limited storage and memory available in home routers.

OpenWrt is configured using a command-line interface (ash shell), or a web interface (LuCI). There are about 3500 optional SW packages available for installation via the `opkg` package management system.

## 2.8 Components of the OpenWRT

The main components are the Linux kernel, `util-linux-ng`, `uClibc` and `BusyBox`. The Linux kernel was already mentioned. `util-linux-ng` is self explanatory - it is a set of linux utilities.

`BusyBox` is a software that provides several stripped-down Unix tools in a single executable file. It runs in a variety of Portable operating system interface (POSIX) environments such as Linux, Android, Berkeley Software Distribution (BSD) family and others, such as proprietary kernels, although many of the tools it provides are designed to work with interfaces provided by the Linux kernel.

`uClibc` is a small C standard library intended for Linux kernel-based operating systems for embedded system and mobile devices.

### 3 GL.inet board

GL.inet Smart Router is a remake of a common TP-Link router TL-WR703N. The board changes include, but are not limited to, increased RAM and Flash memory, custom firmware and what is the most important - 5 usable General-purpose I/O (GPIO) pins exposed to the 2cm pin header for utility. Whole thesis is revolving around taking advantage of this fact. The frequency of Central processing unit (CPU) is 400 Mega-Hertz (MHz) and it is suited for running Linux distributions for embedded devices, preferably OpenWrt or DD-Wrt. The board provides Local area network (LAN) and Wide area network (WAN) connection, as well as other interfaces defined in Institute of Electrical and Electronics Engineers (IEEE). The information about the board are summed up in the table 3–1.

**Table 3–1** The basic characteristics of the GL.inet board

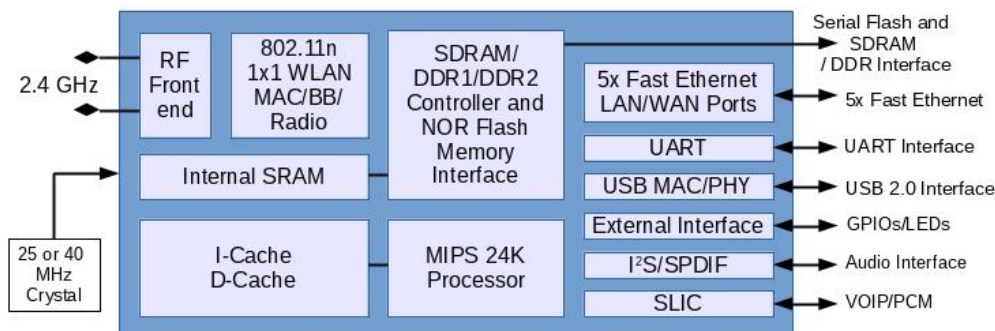
Model	GL-iNet 6408A / 6416A
CPU	Atheros 9331, 400 MHz
RAM	DDR 64Mega-Byte, unit of digital information (MB)
ROM	Flash 8MB (6408A) / 16MB (6416A)
Interface	1 WAN, 1 LAN, 1 USB2.0, 1 Micro USB(Power), 5 GPIO
Wireless	IEEE802.11n/g/b, IEEE 802.3, IEEE 802.3u

#### 3.1 Atheros AR9331 wi-fi System-on-Chip

The Atheros AR9331 is a highly integrated and cost effective IEEE 802.11n 1x1 2.4 GHzertz, the SI unit of frequency (Hz) SoC for Wireless local area network (WLAN) Access Point (AP) and router platforms. The block diagram of the chip can be seen in figure 3–1. Features of this SoC are following:

- Complete IEEE 802.11n 1x1 AP or router in a single chip
- Microprocessor without Interlocked Pipeline Stages (MIPS) 24K processor operating at up to 400 MHz
- External 16-bit Double data rate synchronous DRAM (DDR) or Synchronous dynamic random access memory (SDR) memory interface
- SPI NOR Flash memory support

- No external EEPROM needed
- 4 LAN ports and 1 WAN port IEEE 802.3 Fast Ethernet switch with auto-crossover, auto polarity
- Fully integrated RF front-end including Power amplifier (PA) and Low-noise amplifier (LNA)
- Optional external LNA/PA
- Switched antenna diversity
- High-speed UART for console support
- Integrated Interchip Sound (I<sup>2</sup>S)/Sony-Philips Digital Interface Format (S/PDIF) audio interfaces
- Subscriber line interface circuit (SLIC) for Voice over IP (VOIP)/Pulse code modulation (PCM)
- USB 2.0 host/device mode support
- GPIO/Light emitting diode (LED) support
- Joint test action group (JTAG)-based processor debugging supported
- 25 MHz or 40 MHz reference clock input
- 148-pin, 12 mm x 12 mm dual-row Quad Flat No-leads (LQFP) package



**Figure 3 – 1** The block diagram of the Atheros AR9331 SoC used as a main processing unit on GL.inet board

### 3.2 From TL-WR703N to GL.inet

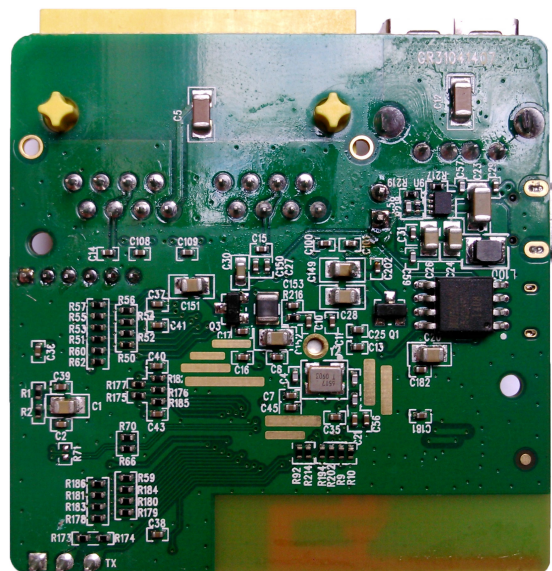
TP-Link TL-WR703N router is a popular choice among HW customisation community because of its cheap price tag compared to processing power and usage of a full-grown Linux distribution. People have figured out how to upgrade RAM / Flash memories or to make use of not used GPIO / UART ports for their own needs. These solutions however were mostly crude and expensive to replicate. The

GL.inet team saw an opportunity to grasp this public knowledge and rolled out their own improved board clone to the market.

Whole printed circuit board of TL-WR703N was remade by the GL.inet team to expose the unused GPIO pins on the SoC, utilize two Ethernet port instead of one and utilize the USB 2.0 port. Memory chips were replaced by their higher capacity alternatives.



**Figure 3 – 2** The front side of the GL.inet board exposing the main Atheros SoC, RAM and interfaces



**Figure 3 – 3** The back side of the GL.inet board exposing the Flash memory and a main voltage regulator



## 4 **ESP8266 wi-fi node**

since it is used, the whole section should be designated to provide some description about it

## 5 Requirements

The requirements for the final device are grouped to the three categories. Mandatory requirements are bound to be met at any cost. Some of the high importance requirements can be skipped or slightly modified, if unreasonable obstacles are found. However, they are all assumed to be completed for well being of the project. Optional requirements will be completed only if possible, given the resources will allow it.

They are also divided to a hardware part and software part. Software is easier to change than hardware and requires hardware to be run on. Software is also limited by the resources provided by the hardware. Therefore, hardware needs to be logically completed first.

### 5.1 Hardware requirements

#### **Mandatory:**

- A. Measure current, voltage and phase angle simultaneously to calculate the real power and the power factor
- B. More measuring devices can be added physically to the system later
- C. Devices under test run at nominal 230 V, 50 Hz that use two-way or three-way EU plug
- D. Protection against the electrical shock, fire hazard and damage caused by power surges

#### **High importance:**

- E. Store the measured data for a minimum of one week
- F. Completely shut the device under test off or back on
- G. Indicate that the device is active (configured and working) with a LED
- H. Handle maximum of 16 A currents drawn by the device under test

#### **Optional:**

- I. Store the measured data on an USB flash disk
- J. Signalize some crossed threshold using sound
- K. Ethernet connection

## 5.2 Software requirements

### Mandatory:

- The Graphical user interface (GUI) running on the web-server
- Add, edit (configure) and remove measurement devices to/from the system
- Present the instantaneous (real) power consumed for each device under test

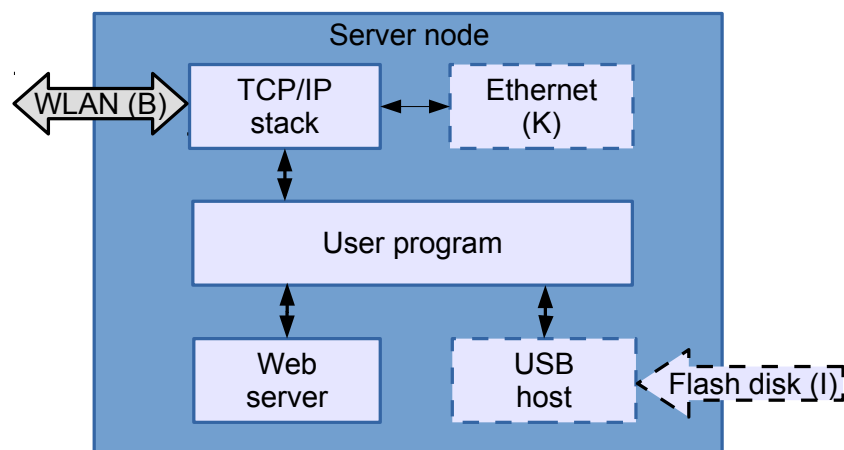
### High importance:

- Graphs of all measured quantities over time
- Authentication mechanism
- Automatic configuration of the new connected measurement devices

### Optional:

- Access to GUI outside of local network
- Fully functional wi-fi repeater included
- Send measured data to the cloud
- Separate administrator (view and change) and user (view only) privileges

## 5.3 System description



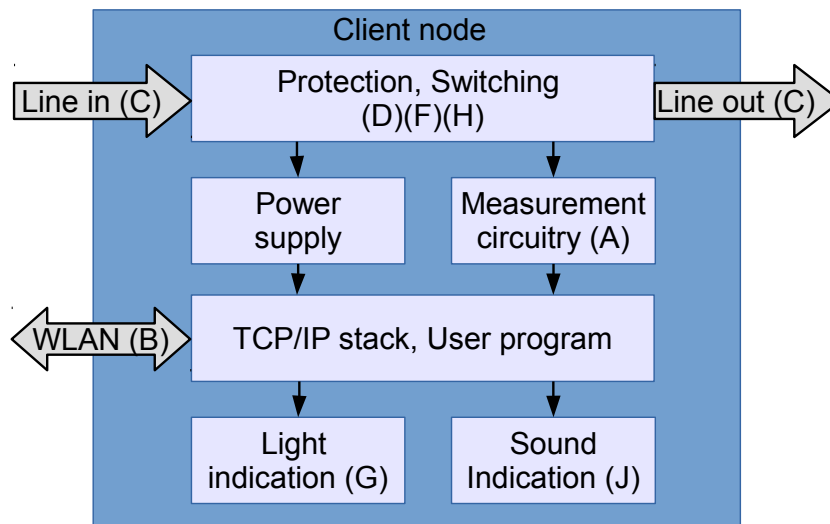
**Figure 5–1** The block diagram of a *server* node of a proposed system, including hardware requirements

The first mandatory software requirement asks for a web server. It is entirely possible for every measurement device to contain its own web server. However, multiple points are requiring devices to work as a **system**. Two common system structures are *centralised* and *decentralised*. Decentralised (peer-to-peer) systems

are harder to build but are more fail-proof. Since fail-proofness is not mentioned in the requirements, centralised system might suffice.

Using centralised system means, that the measurement devices will use one separate device, from now called the **server node**, to do most of the work on the software side. The work includes, but is not limited to, receiving the measured data, storing them, hosting the web server with the GUI containing all necessary options and information, handling the USB or communication with a cloud and so on. The block diagram for a server node, depicting required blocks can be seen in the figure 5–1)

Where there are at least two nodes in a system, they have to communicate together in a particular way, known to both of them. The web server naturally operates over Transmission Control Protocol/Internet Protocol (TCP/IP). Therefore, same networking stack (the way of communication), that is used for communication between the server node and user can be used to communicate to client nodes as well. TCP/IP hardware is ready to be used and is supporting a full-blown networking stack, powering communication over today's networks.



**Figure 5–2** The block diagram of a *client* node of a proposed system, including hardware requirements

The measurement devices, from now on called **client nodes** will consist of blocks of the remaining hardware requirements. The resulting block diagram can be seen in the figure 5–2)

## 5.4 The TCP/IP networking protocol

TCP/IP consists of two layers. The higher layer, Transmission Control Protocol (TCP), manages the assembling of a message or file into smaller packets that are transmitted over the Internet and received by a TCP layer that reassembles the packets into the original message. The lower layer, Internet Protocol (IP), handles the address part of each packet so that it gets to the right destination. Each gateway computer / device on the network checks this address to see where to forward the message. Even though some packets from the same message are routed differently than others, they'll be reassembled at the destination.

TCP/IP uses the client/server model of communication in which a computer user (a client) requests and is provided a service (such as sending a Web page) by another computer (a server) in the network. TCP/IP communication is primarily point-to-point, meaning each communication is from one point (or host computer) in the network to another point or host computer. TCP/IP and the higher-level applications that use it are collectively said to be *stateless* because each client request is considered a new request unrelated to any previous one (unlike ordinary phone conversations that require a dedicated connection for the call duration). Being stateless frees network paths so that everyone can use them continuously.

## 6 Main part of Thesis

## 7 Conclusion

Táto časť záverečnej práce je povinná. Autor uvedie zhodnotenie riešenia. Uvedie výhody, nevýhody riešenia, použitie výsledkov, ďalšie možnosti a pod., prípadne načrtne iný spôsob riešenia úloh, resp. uvedie, prečo postupoval uvedeným spôsobom.

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# Appendices

Appendix A Prílohy

Appendix B Bibliografické odkazy

Appendix C Vytvorenie zoznamu skratiek a symbolov

Appendix D

## Appendix A

### Prílohy (Appendices)

Táto časť záverečnej práce je povinná a obsahuje zoznam všetkých príloh vrátane elektronických nosičov. Názvy príloh v zozname musia byť zhodné s názvami uvedenými na príslušných prílohách. Tlačené prílohy majú na prvej strane identifikačné údaje – informácie zhodné s titulnou stranou záverečnej práce doplnené o názov príslušnej prílohy. Identifikačné údaje sú aj na priložených diskoch alebo disketách. Ak je médií viac, sú označené aj číselne v tvare  $I/N$ , kde  $I$  je poradové číslo a  $N$  je celkový počet daných médií. Zoznam príloh má nasledujúci tvar:

**Appendix A** CD médium – záverečná práca v elektronickej podobe, prílohy v elektronickej podobe.

**Appendix B** Používateľská príručka

**Appendix C** Systémová príručka

Prílohová časť je samostatnou časťou kvalifikačnej práce. Každá príloha začína na novej strane a je označená samostatným písmenom (Appendix A, Appendix B, ...). Číslovanie strán príloh nadväzuje na číslovanie strán v hlavnom texte. Pri každej prílohe sa má uviesť prameň, z ktorého sme príslušný materiál získali.

## Appendix B

### Bibliografické odkazy

Táto časť záverečnej práce je povinná. V zozname použitej literatúry sa uvádzajú odkazy podľa normy STN ISO 690–2 (01 0197) (Informácie a dokumentácia. Bibliografické citácie. Časť 2: Elektronické dokumenty alebo ich časti, dátum vydania 1. 12. 2001, ICS: 01.140.20). Odkazy sa môžu týkať knižných, časopiseckých a iných zdrojov informácií (zborníky z konferencií, patentové dokumenty, normy, odporúčania, kvalifikačné práce, osobná korešpondencia a rukopisy, odkazy cez sprostredkujúci zdroj, elektronické publikácie), ktoré boli v záverečnej práci použité.

Existujú dva hlavné spôsoby citovania v texte.

- Citovanie podľa mena a dátumu.
- Citovanie podľa odkazového čísla.

*Preferovanou metódou citovania* v texte vysokoškolskej a kvalifikačnej práce je podľa normy ISO 7144 citovanie podľa mena a dátumu. V tomto prípade sa zoznam použitej literatúry upraví tak, že za meno sa pridá rok vydania. Na uľahčenie vyhľadávania citácií sa zoznam vytvára v abecednom poradí autorov.

Príklad: ... podľa je táto metóda dostatočne rozpracovaná na to, aby mohla byť všeobecne používaná v ...

Druhý spôsob uvedenia odkazu na použitú literatúru je uvedenie len čísla tohto zdroja v hranatých zátvorkách bez mena autora (autorov) najčastejšie na konci príslušnej vety alebo odstavca.

Príklad: ... podľa [13] je táto metóda dostatočne rozpracovaná na to, aby mohla byť všeobecne používaná v ... ako je uvedené v [14].

Citácie sú spojené s bibliografickým odkazom poradovým číslom v tvare indexu alebo čísla v hranatých zátvorkách. Odkazy v zozname na konci práce budú usporiadané podľa týchto poradových čísel. Viacero citácií toho istého diela bude mať rovnaké číslo. Odporúča sa usporiadať jednotlivé položky v poradí citovania alebo podľa abecedy.

Rôzne spôsoby odkazov je možné dosiahnuť zmenou voľby v balíku `natbib`:

```
% Citovanie podľa mena autora a roku
\usepackage[] {natbib} \citestyle{chicago}
% Možnosť rôznych štýlov citácií. Príklady sú uvedené
% v preambule súboru natbib.sty.
% Napr. štýly chicago, egs, pass, angeo, nlinproc produkujú
% odkaz v tvare (Jones, 1961; Baker, 1952). V prípade, keď
% neuvedieme štýl citácie (vynecháme \citestyle{ }) v "options"
% balíka natbib zapíšeme voľbu "colon".
```

Keď zapneme voľbu `numbers`, prepneme sa do režimu citovania podľa odkazového čísla.

```
% Metoda číselných citácií
\usepackage [numbers] {natbib}
```

Pri zápise odkazov sa používajú nasledujúce pravidlá:

Pri využívaní informácií z elektronických dokumentov treba dodržiavať tieto zásady:

- uprednostňujeme autorizované súbory solídnych služieb a systémov,
- zaznamenáme dostatok informácií o súbore tak, aby ho bolo opäť možné vyhľadať,
- urobíme si kópiu použitého prameňa v elektronickej alebo papierovej forme,
- za verifikovateľnosť informácií zodpovedá autor, ktorý sa na ne odvoláva.

Pre zápis elektronických dokumentov platia tie isté pravidlá, ako pre zápis „klasických“. Navyše treba uviesť tieto údaje:

- druh nosiča [online], [CD-ROM], [disketa], [magnetická páska]
- dátum citovania (len pre online dokumenty)
- dostupnosť (len pre online dokumenty)

Poradie prvkov odkazu je nasledovné: Autor. Názov. In Názov primárneho zdroja: Podnázov. [Druh nosiča]. Editor. Vydanie alebo verzia. Miesto vydania : Vydavateľ, dátum vydania. [Dátum citovania]. Poznámky. Dostupnosť. ISBN alebo ISSN.

## Appendix C

### Vytvorenie zoznamu skratiek a symbolov

Ak sú v práci skratky a symboly, vytvára sa *Zoznam skratiek a symbolov* (a ich dešifrovanie). V prostredí L<sup>A</sup>T<sub>E</sub>Xu sa takýto zoznam ľahko vytvorí pomocou balíka `nomenc1`. Postup je nasledovný:

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## Curriculum vitae

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